



ALLFLEXDOT 12PACK 4131A

ALLFLEXDOP

Maximum dexterity and sensitivity safety gloves for the most delicate handling

The seamless ALLFLEX gloves of Safety Jogger are designed for light and delicate applications for which a maximum of agility and sensitivity are an absolute must. Excellent for delicate assembly and other light handling. Nylon spandex liner with black micro foam nitrile coating for precision handling in dry conditions.

Performance level	4131A
Liner	15 GAUGE NYLON + SPANDEX
Coating	FOAM NITRILE / NITRILE DOTS
Category	TSF-Touchscreen function
Size range	EU 6-12
Sample weight	0.120 kg
Norms	EN ISO 21420:2020 EN 388:2016



EN ISO 21420

EN 388:2016



Industries:

Assembly, Automotive, Chemical, Cleaning, Construction, Industry, Logistics, Mining, Oil & Gas, Tactical

Touchscreen compatible

You can use your smartphone or tablet without taking off the gloves, thanks to their special coating.

DMF-free PU

Made from polyurethane that doesn't contain DMF (a chemical that can be harmful), which means they are safe to use.



BLK

Performance level 4131A

EN388:2016	0	1	2	3	4	5
a. Abrasion resistance (cycles)	< 100	100	500	2000	8000	-
b. Cut resistance (factor)	< 1.2	1.2	2.5	5.0	10.0	20.0
c. Tear resistance (newton)	< 10	10	25	50	75	-
d. Puncture resistance (newton)	< 20	20	60	100	150	-

EN ISO 13997 (TDM-100 test)	A	B	C	D	E	F
e. Straight blade cut resistance (newton)	2	5	10	15	22	30

- a. Abrasion resistance: based on the number of cycles required to rub through the sample glove.
- b. Cut resistance: based on the number of cycles required to cut through the sample at a constant speed with a rotating blade.
- c. Tear resistance: based on the amount of force required to tear the sample.
- d. Puncture resistance: based on the amount of force required to pierce the sample with a standard sized point.
- e. Cut resistance according TDM100 test based on the number of cycles required to cut through the sample at a constant speed with a sliding blade.

**SAFETY
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WORKS

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INDUSTRIAL PROFESSIONAL TACTICAL TIGER GRIP

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